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Building a Software-Defined-Network Using K8s API Machinery and Controllers

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Project: https://github.com/MikeSpreitzer/kube-examples/tree/add-kos/staging/kos

Why do this?

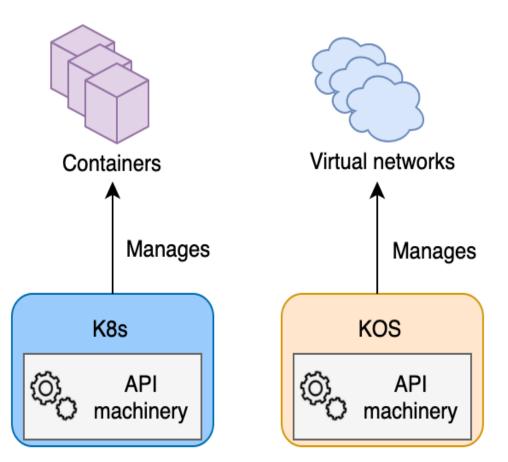
Test and demonstrate that **K8s controller pattern** and **API machinery** are general building blocks, not just for K8s.

We built **KOS** (K8s OvS SDN).

KOS manages VXLAN virtual networks.

NOT for production.

Runs only on Linux.



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Agenda



- 1. VXLAN.
- 2. K8s controller pattern.
- 3. KOS API.
- 4. KOS architecture.
- 5. Interesting, general challenges.

VXLAN

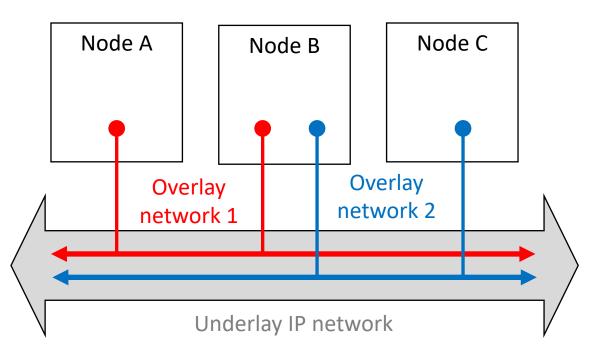


Goal: overlay virtualized Ethernet networks over IP underlay networks.

Features:

- Isolation and scalability.
- Tunneling-via-encapsulation protocol.

KOS dynamically configures VXLAN overlay networks.



K8s controller pattern

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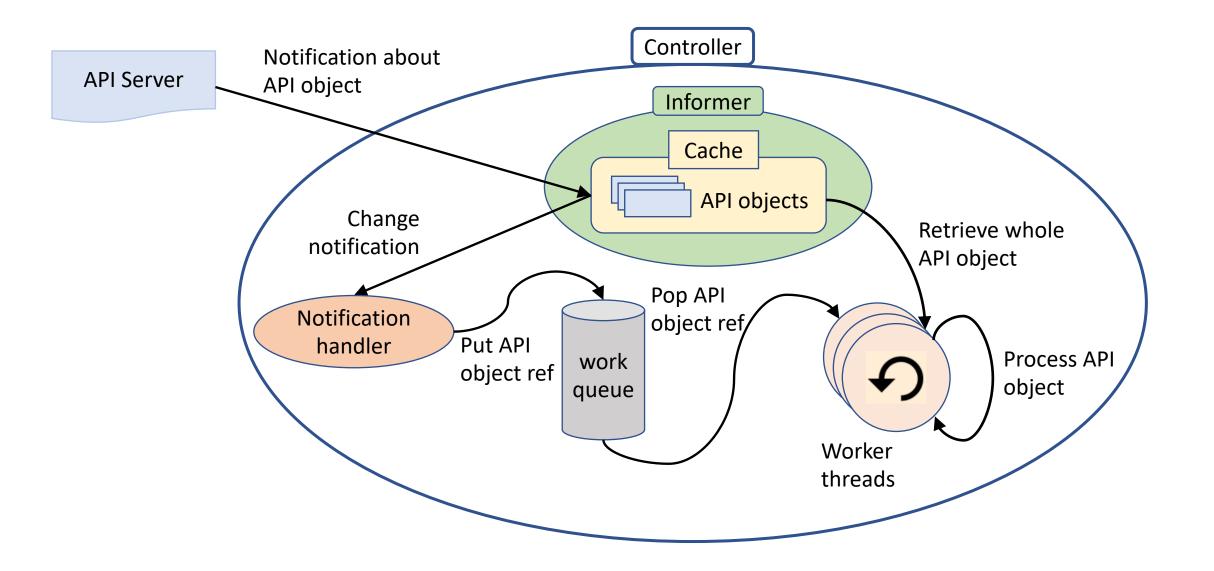
An API object has two sections:

- desired state (*spec*)
- observed state (*status*)

K8s control plane is a set of control loops (*controllers*) that:

- listen for API objects notifications (create/update/delete).
- modify "real world" to drive it towards API objects desired state.
- write back observed, real world state into API object status (with MVCC).

Anatomy of a K8s controller



2

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Like in K8s, users interact with KOS via CRUD operations on API objects.

KOS defines three custom API object types:

- **Subnet**: an IPv4 subnet in a VXLAN virtual network.
- NetworkAttachment (NA): an interface on a VXLAN virtual network.
- IPLock: more details later.

Custom types are implemented in custom API servers.



apiVersion: network.example.com/v1alpha1

```
kind: Subnet
```

```
metadata:
    name: s1
    namespace: ns1
spec:
    vni: 1
    ipv4: 192.168.10.0/24
status:
    validated: true
```

apiVersion: network.example.com/v1alpha1 kind: NetworkAttachment metadata: name: nal namespace: nsl spec: subnet: s1 node: node1 status: questIP: 192.168.10.0 guestMAC: 02:a8:0a:00:00:01 addressVNI: 1 hostIP: 10.190.65.131

NA implementation



KOS implements a *NA* with:

- 1. A virtual IP address.
- 2. A virtual MAC address.
- 3. A Linux network interface on the underlay node of the NA.

Plus...

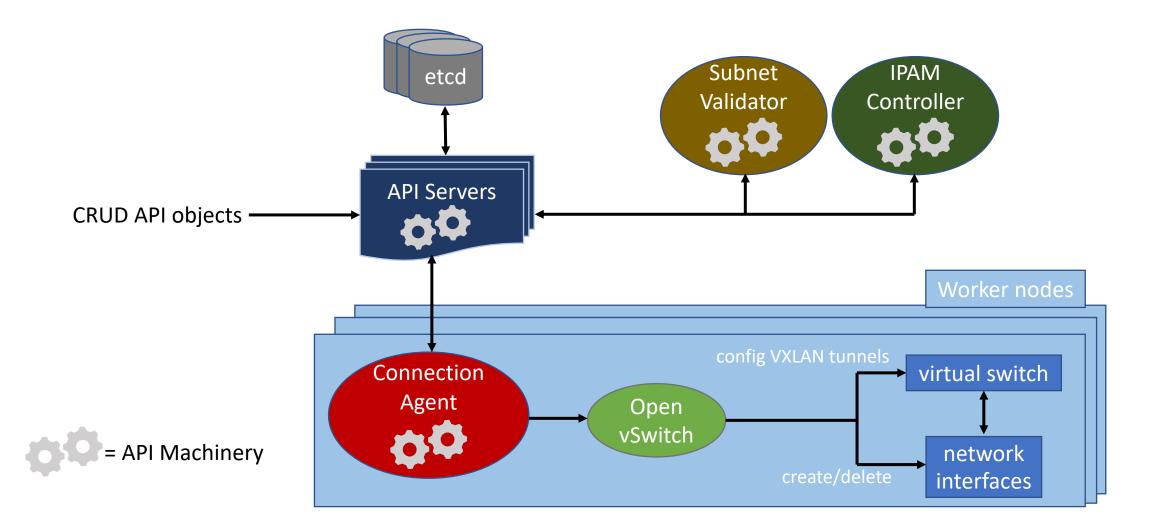
On every underlay node, there's an OvS switch that supports VXLAN.

KOS:

- 1. connects the network interface to the switch.
- 2. sets up the switch to ENCAP/DECAP all traffic from/to the network interface.

KOS architecture



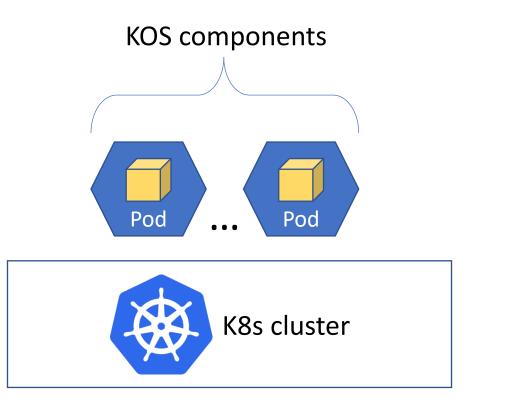


KOS Deployment

KOS runs as a K8s workload.

But...

could also be deployed on its own.



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Multi-object invariants pt. 1

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For Subnets with same *vni*:

- (A): CIDR blocks MUST NOT overlap.
- (B): K8s namespaces must be the same.

Creation of a subnet that leads to a violation of (A) or (B) should fail.

So... validation must happen before creation, in API servers.

Problem of enforcing an invariant across multiple API objects of same type.

```
1 func isValid(S subnet) bool {
2 ES = all existing subnets with same VNI as S
3 for each subnet SR in ES {
4    if S and SR are in conflict {
5      return false
6    }
7  }
8 return true
9 }
```

Problem: conflicting subnets could be validated in parallel.

This validation is unreliable if done before subnet is created.



Can't guarantee that no conflicting subnets are created \otimes .

Next best thing: if conflicting subnets exist, consumers use at most one. How?

Introduce *status.validated* field.

A subnet can be used only if *status.validated* = *true*.

If conflicting subnets exist, *at most one* has *status.validated* = *true*.

Multi-object invariants pt. 4

Subnet Validator:

- writes Subnets' *status.validated*.
- singleton controller.
- has an informer on Subnets.

```
1 func isValid(S subnet) bool {
2 ES = all existing subnets with same VNI as S
3 for each subnet SR in ES {
4 if S and SR are in conflict {
5 return false
6 }
7 }
8 return true
9 }
```



The Subnet Validator has one advantage over the API sever.

When it validates a Subnet S1, S1 already exists.

API objects are created (persisted to etcd) sequentially.

If two conflicting subnets S1 and S2 are created, one (S2) is created last.

When the validator considers S2, S1 already exists.

```
1 func isValid(S subnet) bool {
2 ES = live list: all existing subnets with same VNI as S
3 for each subnet SR in ES {
4 if S and SR are in conflict {
5 return false
6 }
7 }
8 return true
9 }
```

Can't retrieve existing subnets from informer cache:

- Two Subnet Validators might run at the same time.
- Informer caches are populated with no cross-object ordering guarantee.

Multi-object invariants pt. 7

Assume that:

- informer lists are used.
- two conflicting subnets S1 and S2 are created.
- two Subnet Validators V1 and V2 are running.

What might go wrong:

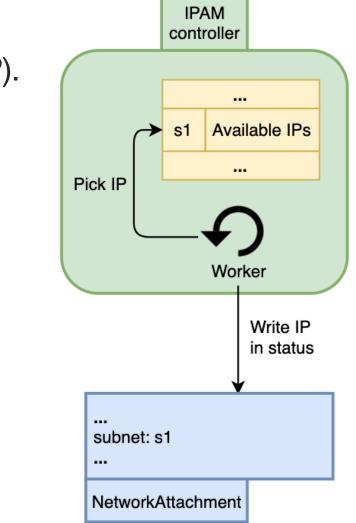
- V1 might validate S1 first without seeing S2.
- V2 might validate S2 first without seeing S1.

So...

Need to use live lists (against the API server): correct but less efficient.

IPAM pt. 1

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IPAM controller:

- assigns virtual IPs to NAs (written into status.guestIP).
- singleton (best-effort).

Has informers on:

- Subnets.
- NAs.

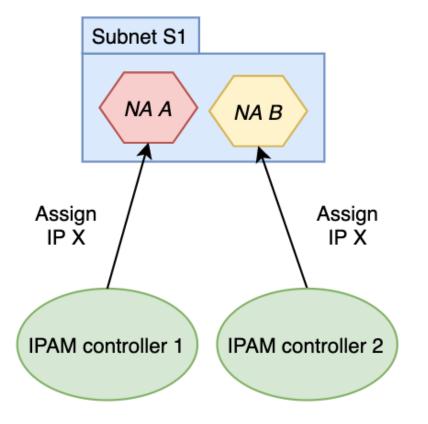
Picks IPs from a per-subnet, in-memory cache of available IPs.

IPAM pt. 2

Multiple instances could run at once => risk of virtual IPs collisions!

So...

Local cache of available IPs not enough.



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IPAM pt. 3



Solution: before assigning an IP, acquire a global lock on it.

Locking implemented as creation of an *IPLock* custom API object.

IPLock on IP X on VNI Y has name "Y-X".

K8s forbids multiple API objects with same namespaced name and kind.

So...

Impossible to assign twice same IP: creation of 2nd IPLock fails.

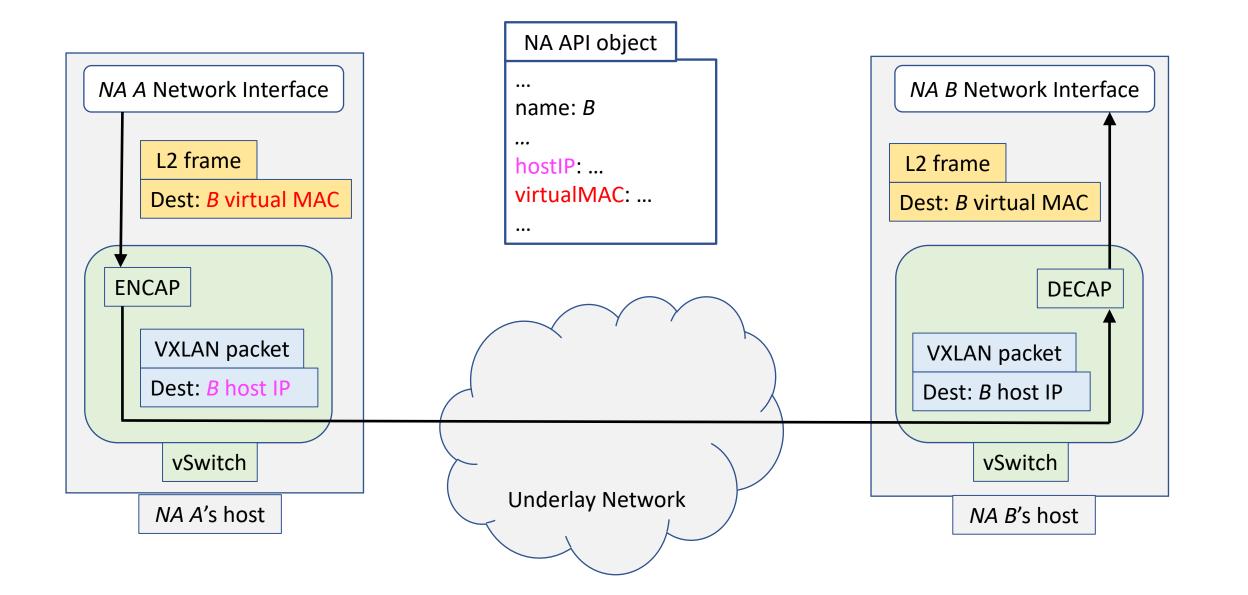
Connection Agent (CA) on node N implements local NAs.

So... has informer on local NAs.

If *NA* with VNI *X* exists on node *N*, VNI *X* is "relevant" on *N*.

CA on N also needs to be notified of remote NAs with relevant VNIs.

Why? To ensure local NAs can send data to remote NAs.



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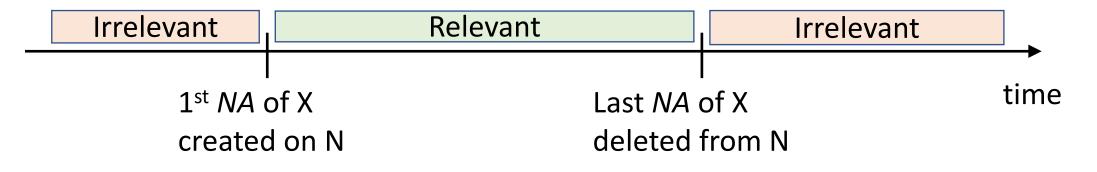
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Set of relevant VNIs on a node is dynamic.

Relevance of VNI X to Node N:



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CA needs to be notified ONLY of remote NAs with relevant VNIs.

Informers support filtering.

Can use a single informer to filter on relevant VNIs? No: informer filtering is static.

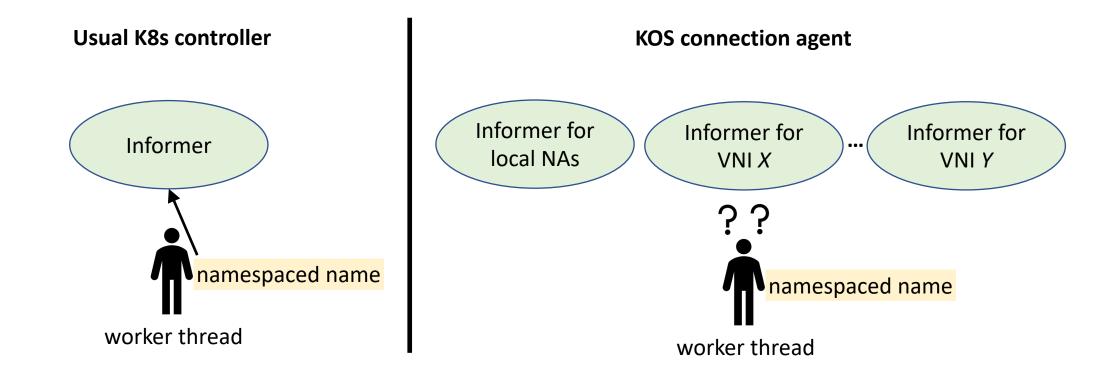
How to synthesize dynamic filtering?

Solution: a dedicated informer for each relevant VNI.

Informers are started/stopped as VNIs become relevant/irrelevant.

A CA has potentially many informers on NAs.

Worker threads don't know from which informer to retrieve NAs!



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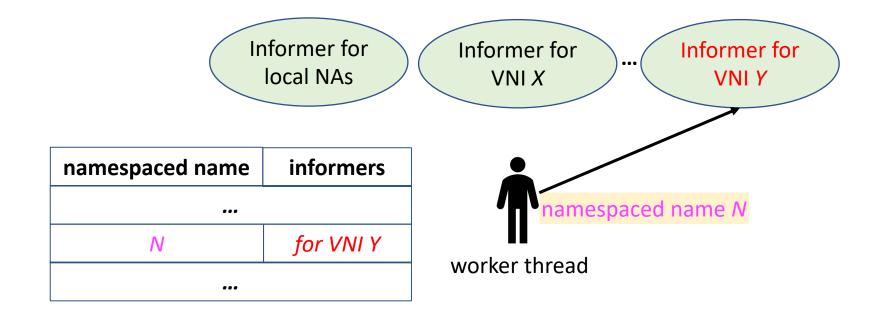
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Solution: map from namespaced name to informers where the NA is.

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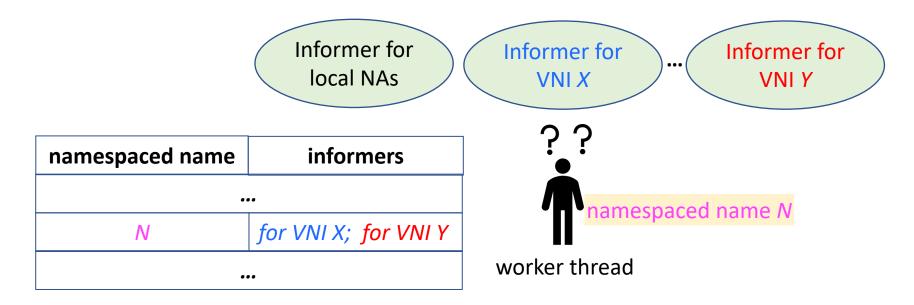
The map is updated by informer notification handlers.



During transients, a NA can be in more than one informer, because:

- *NA* can be updated => VNI can change.
- No cross-informer ordering guarantee for notifications.

What does a worker thread do in these cases?



If NA in more than one informer, worker gives up on processing it.

Only one informer stores up-to-date version of the NA.

Delete notifications for old versions will come => ambiguity will be solved.

Delete notifications enqueue *NA*'s namespaced name => *NA* is re-processed.



We built an SDN proof of concept with K8s API machinery and controller pattern.

The result is that it can be done with relatively small effort.

Some interesting challenges emerged:

- enforcing invariants across API objects of the same type (subnets validation).
- IP assignments while avoiding IP collisions and IP leaks.
- synthesis of dynamic filtering from informers for efficient delivery of notifications.

We believe such challenges apply not just to KOS, and required special care and creative solutions.





Thank you for your attention.

Q&A.

