

Zephyr Project: Unlocking IoT Innovation with an Open Source RTOS

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Customer

nRF52832

Bluetooth LE

Lighting

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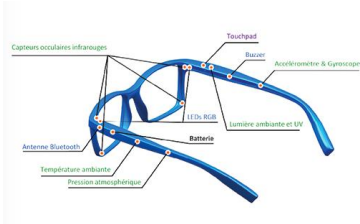
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“Because we required multi-tasking, the Nordic SoC's Zephyr RTOS [real-time operating system] support was also important.” - Wu Tianji, CTO at Phantom

Products Running Zephyr Today



Ellcie-Healthy Smart
Connected Eyewear



Grush Gaming
Toothbrush



hereO
Smartwatch



Rigado IoTGateway



ProGlove
Scanning Gloves



Adero tracking devices



GNARBOX 2.0 SSD



RUUVI node



GEPS



Point Home Alarm



Blocks Modular Smartwatch



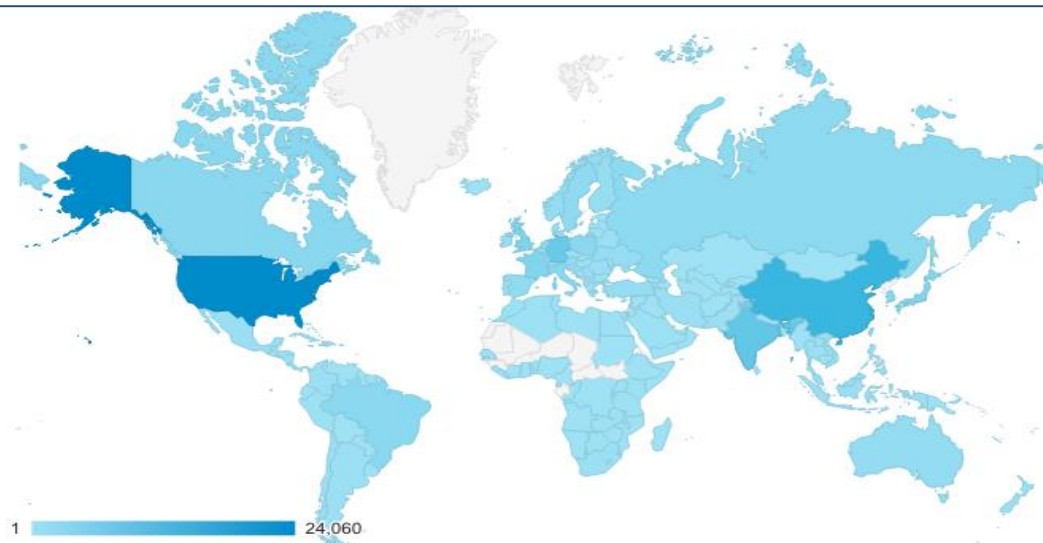
Intellinium Safety Shoes



Anicare reindeer tracker



HereO Core Box



1 year of
traffic to
zephyr.org
website

Primary Dimension: **Country** [City](#) [Continent](#) [Sub Continent](#)

Secondary dimension [▼](#)

[advanced](#) [Grid](#) [Chart](#) [Table](#) [Map](#) [Print](#)

Country ?	Users ? ↓	Sessions ?	Pages / Session ?	Avg. Session Duration ?	% New Sessions ?	Bounce Rate ?
	107,341 % of Total: 100.00% (107,341)	219,112 % of Total: 100.00% (219,112)	2.85 Avg for View: 2.85 (0.00%)	00:03:15 Avg for View: 00:03:15 (0.00%)	48.61% Avg for View: 48.52% (0.20%)	56.43% Avg for View: 56.43% (0.00%)
1. United States	24,060 (21.78%)	43,255 (19.74%)	2.80	00:02:59	53.86%	57.70%
2. China	11,898 (10.77%)	30,959 (14.13%)	3.19	00:04:20	36.51%	49.15%
3. India	7,497 (6.79%)	14,760 (6.74%)	2.56	00:03:09	49.99%	58.70%
4. Germany	6,737 (6.10%)	12,192 (5.56%)	2.86	00:03:06	52.57%	58.11%
5. United Kingdom	3,905 (3.53%)	6,459 (2.95%)	2.62	00:02:31	58.28%	58.38%

Pulse

Contributors

Community

Traffic

Commits

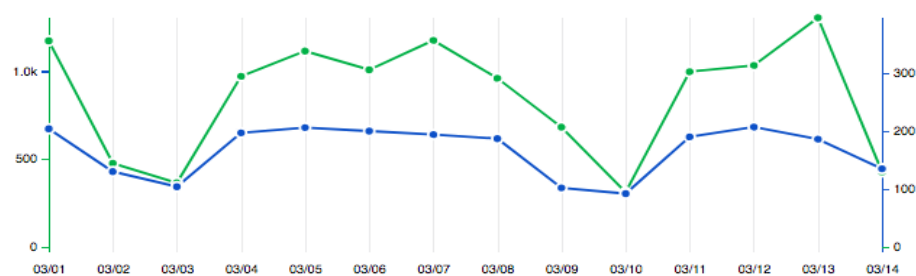
Code frequency

Dependency graph

Network

Forks

Git clones



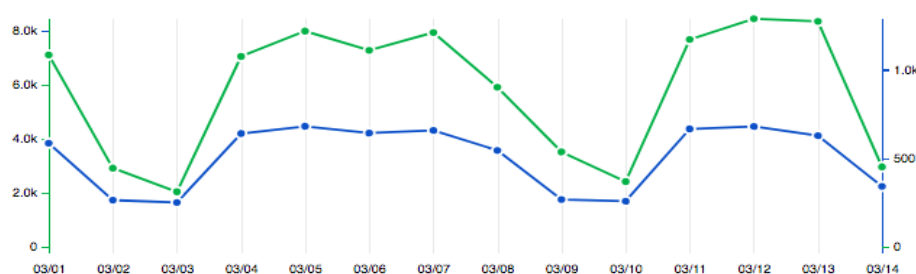
11,972

Clones

908

Unique cloners

Visitors



81,557

Views

4,250

Unique visitors

2 weeks of
traffic to
github.com/
zephyr code
repository



Zephyr Project:

- **Open source** real time operating system
- **Vibrant Community** participation
- Built with **safety and security** in mind
- **Cross-architecture** with growing developer tool support
- **Vendor Neutral** governance
- **Permissively** licensed - Apache 2.0
- **Complete**, fully integrated, highly configurable, **modular** for **flexibility**, better than roll-your-own
- **Product** development ready using LTS includes security updates
- **Certification** ready with Auditable

Open Source, RTOS, Connected, Embedded
Fits where Linux is too big

Zephyr OS

3rd Party Libraries

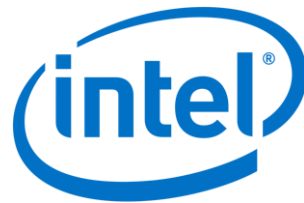
Application Services

OS Services

Kernel

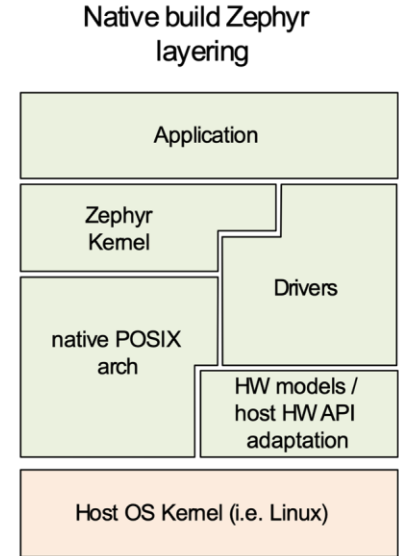
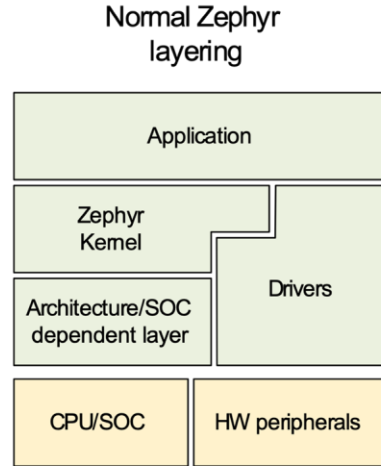
HAL

Zephyr Supported Hardware Architectures



Native execution on a POSIX-compliant OS

- Build Zephyr as native Linux application
- Enable large scale simulation of network or BLE tests without involving HW
- Improve test coverage of application layers
- Use any native tools available for debugging and profiling
- Develop GUI applications entirely on the desktop
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Sample of Board Support



SiFive HiFive1



Arduino Due



Nucleo 103RB



NRF51



Nucleo64 L476RG



Nucleo F411RE



NRF52 pca10040



Nucleo F334R8



Synopsys EMSK



Arduino 101



Minnowboard



Altera MAX10



Nucleo 401RE



Hexiwear



ARM V2M MPS2



STM3210c



Atmel SAM E70



Adafruit Feather



Galileo



NXP FRDM K64F



NRF52



Seed Carbon



TI Launchpad Wifi



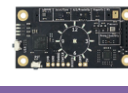
BBC Microbit



STM32373c



Redbear BLE Nano



96b Neon Key



Quark D2000



STM32 Olimexino



STM Mini A15



Seed Nitrogen



ARM V2M Beetle



Zedboard Pulpino



NXP FRDM-KW41Z



tinyTILE



NXP i.MX RT1050

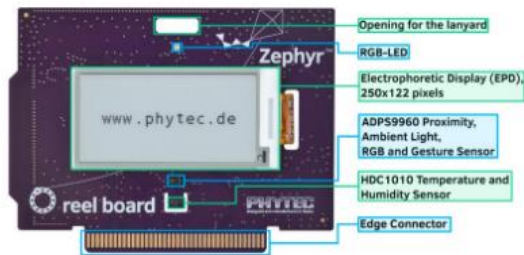
170 BOARDS TODAY WITH MORE ON WAY...

<http://docs.zephyrproject.org/boards/boards.html>

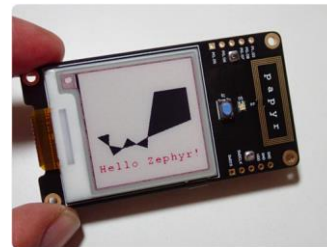
Boards Shipping with Zephyr Today



Antmicro Badge

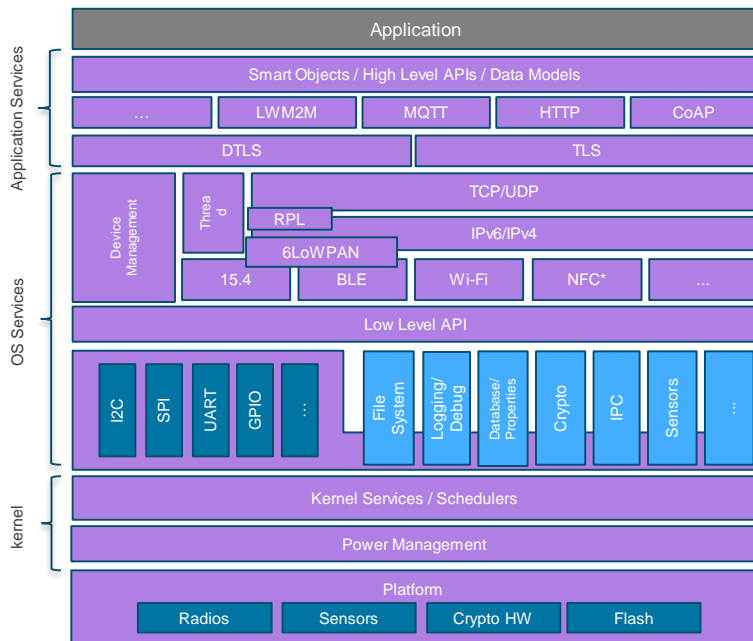


Phytec Reel Board



Electronuts Papyr

Architecture

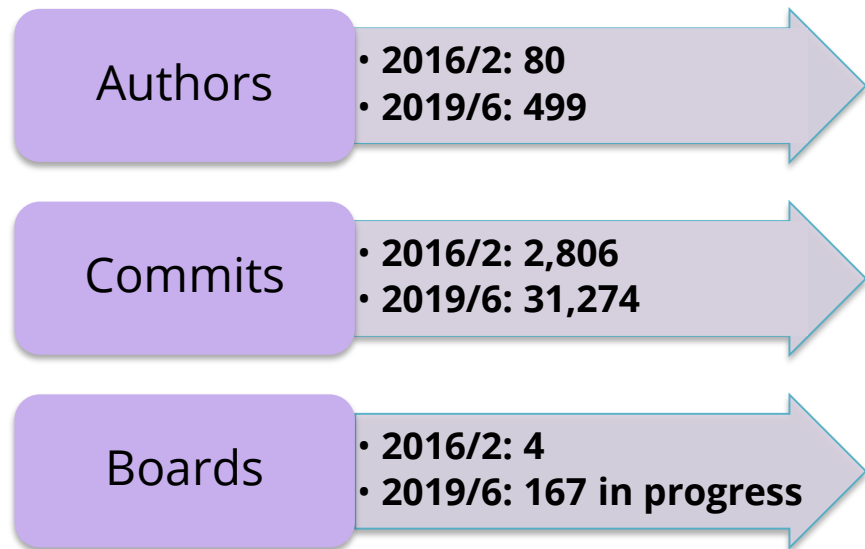


- Highly Configurable, Highly Modular
- Cooperative and Pre-emptive Threading
- Memory and Resources are typically statically allocated
- Integrated device driver interface
- Memory Protection: Stack overflow protection, Kernel object and device driver permission tracking, Thread isolation
- Bluetooth® Low Energy (BLE 4.2, 5.0) with both controller and host, BLE Mesh
- Native, fully featured and optimized networking stack

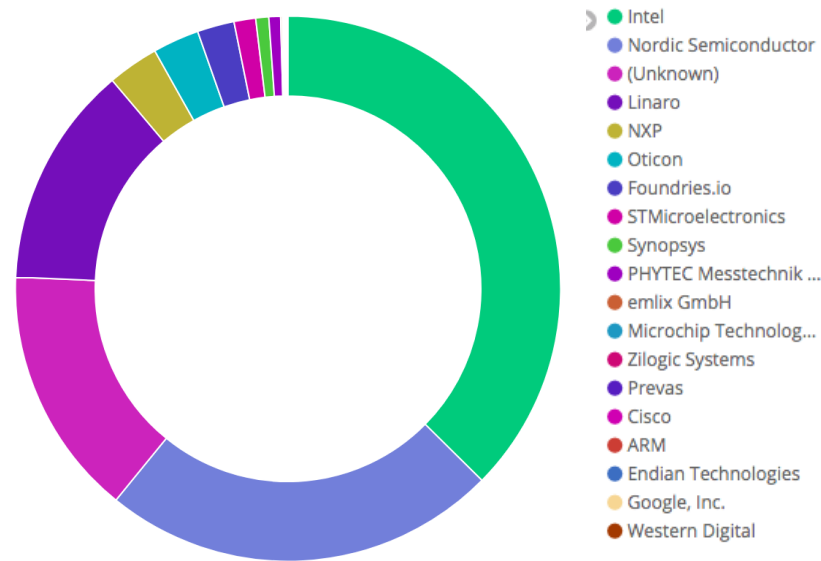
Fully featured OS allows developers to focus on the application

Growing a Diverse Community!

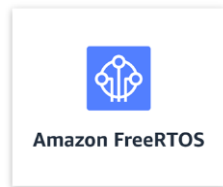
Lifetime project participation



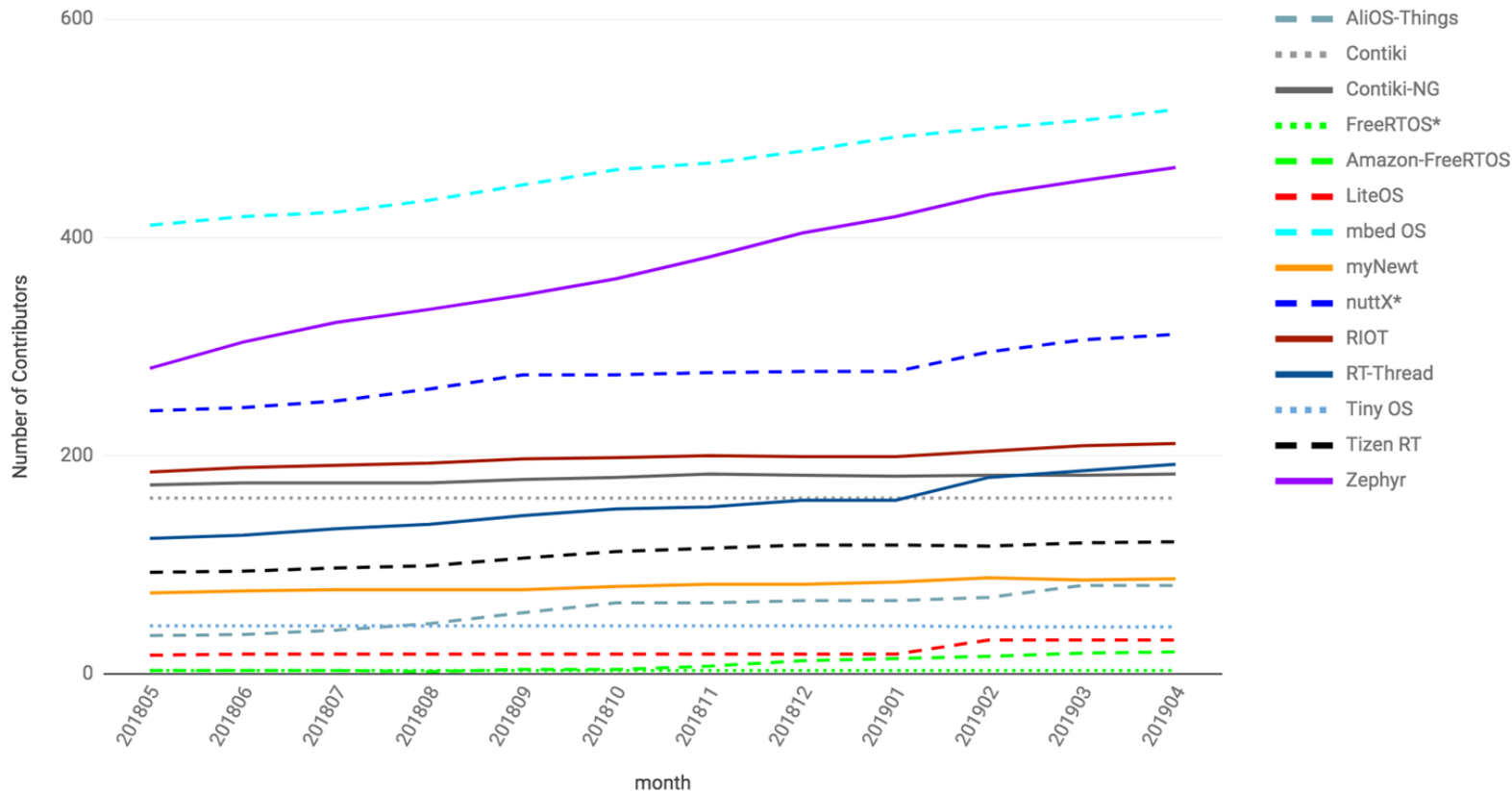
1.14 (LTS) release participation



Open Source OS/RTOS Options Today

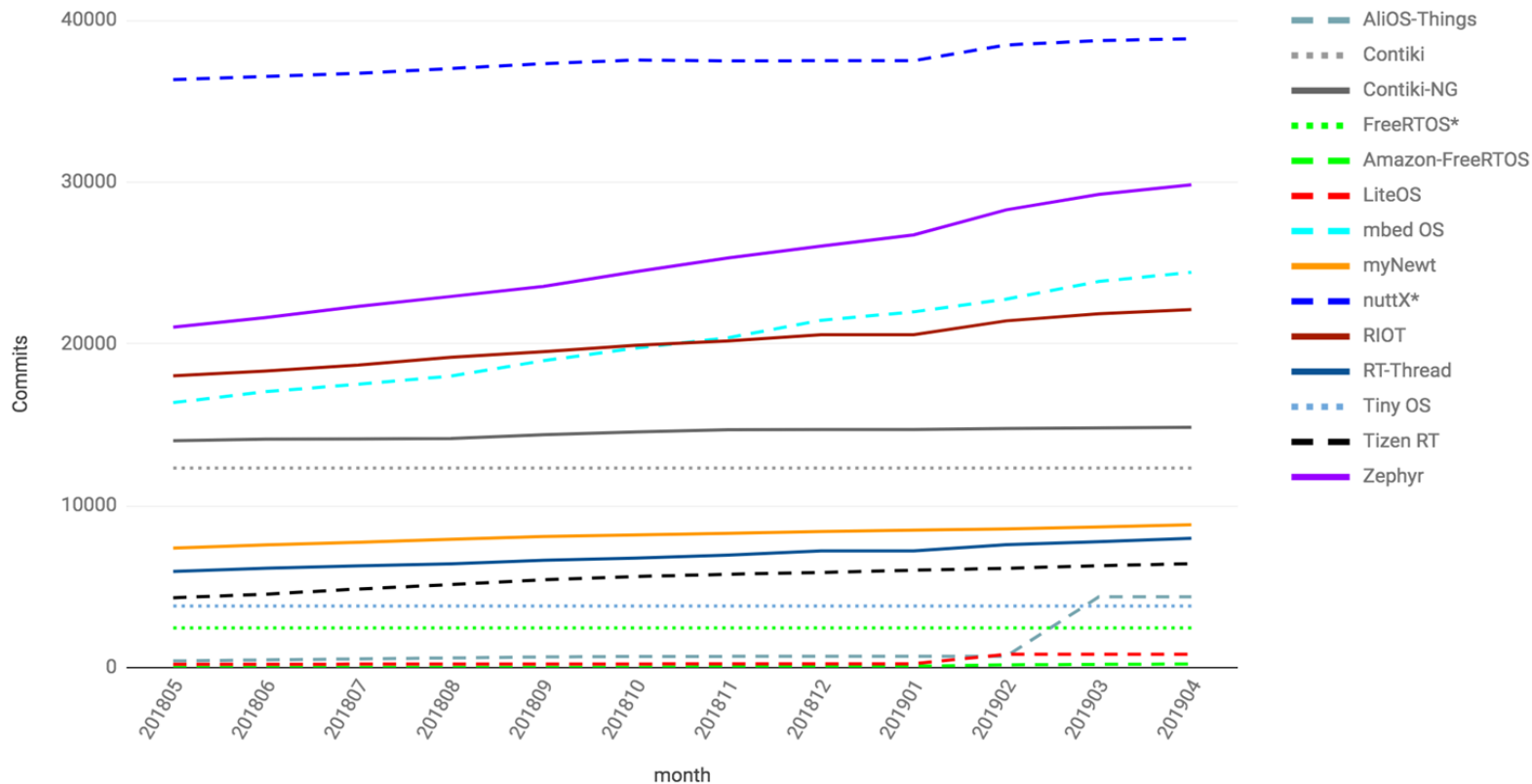


Operating System Contributors



Source: Data as of 2019-4-25 from github (* from openhub.net)

Total Commits by Operating System



Source: Data extracted on 2019-4-25 from github (* from openhub.net)

Operating System	First Commit	Controls Commits	Copyright Treatment	Declared License	Total Contribs	Total Commits	Commits in last month
AliOS-Things	2017/09	Alibaba	Assign	Apache-2.0	81	4,374	0
Contiki	2006/06	community		BSD-3-Clause	161	12,327	0
Contiki-NG	2017/10	community	Retain	BSD-3-Clause	184	14963	8
FreeRTOS*	2004/07	Richard Barry	Assign	GPL-2.0 w/ FreeRTOS exception	3	2,441	0
Amazon-FreeRTOS	2017/11	Amazon	Assign	MIT	35	1529	328
LiteOS	2016/09	Huawei	Assign	BSD-3-Clause	31	816	0
mbed OS	2013/02	ARM	Assign → Retain	Apache-2.0 or BSD-3-Clause	525	25,153	207
myNewt	2015/06	community	Aggregate	Apache-2.0	87	8,829	139
nuttX*	2007/?	Gregory Nutt	Assign	BSD-variant	315	39,013	158
RIOT	2010/09	community	Retain	LGPL-2.1	215	22,393	158
RT-Thread	2009/06	community	Aggregate	?? GPL-2.0 → Apache-2.0	198	8,175	107
Tiny OS	2004/10	community		BSD-3-Clause	43	3,809	21
Tizen RT	2015/04	Samsung	Assign	?? BSD-variant → Apache-2.0	128	6,839	129
Zephyr	2014/11	community	Retain	Apache-2.0	499	31,229	645

Zephyr in RTOS Landscape 2019/6/23

#2

**Total
Contributors**

Rank	RTOS	#
1	mbed OS	525
2	Zephyr	499
3	nuttX	315

#2

**Total
Commits**

Rank	RTOS	#
1	nuttX	39,013
2	Zephyr	31,229
3	mbed OS	25,153

#1

**Commits to Master
(last 30 days)**

Rank	RTOS	#
1	Zephyr	645
2	Amazon FreeRTOS	328
3	mbed OS	207

Zephyr Ecosystem



Zephyr OS

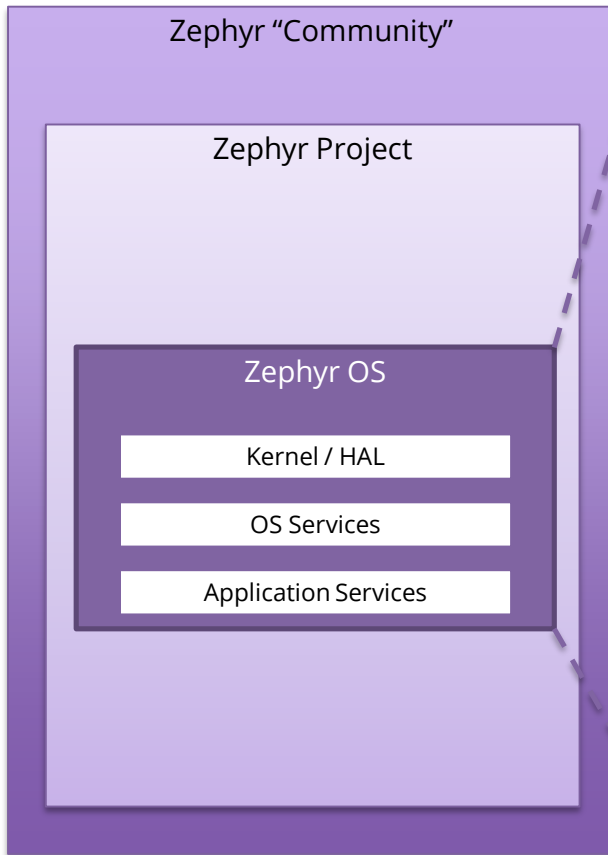
- The kernel and HAL
- OS Services such as IPC, Logging, file systems, crypto

Zephyr Project

- SDK, tools and development environment
- Additional middleware and features
- Device Management and Bootloader

Zephyr Community

- 3rd Party modules and libraries
- Support for Zephyr in 3rd party projects, for example: Jerryscript, Micropython, Iotivity



Kernel / HAL

- Scheduler
- Kernel objects and services
- low-level architecture and board support
- power management hooks and low level interfaces to hardware

OS Services and Low level APIs

- Platform specific drivers
- Generic implementation of I/O APIs
- File systems, Logging, Debugging and IPC
- Cryptography Services
- Networking and Connectivity
- Device Management

Application Services

- High Level APIs
- Access to standardized data models
- High Level networking protocols

Developer Tools...



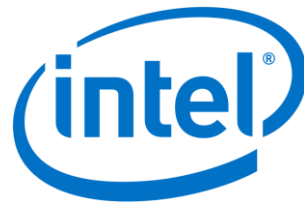
RENODE™

by:  antmicro
EMBEDDED SYSTEMS



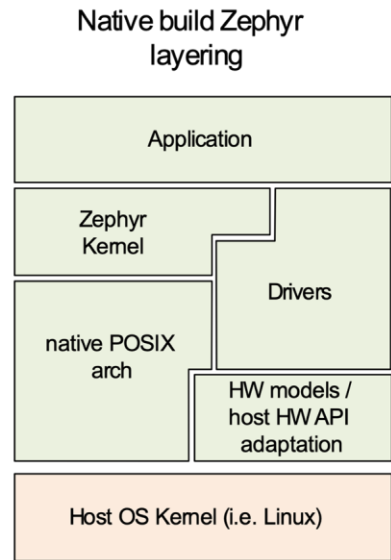
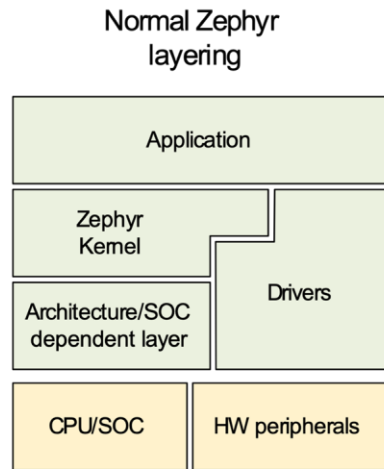
Synopsys
DesignWare
ARC Development
Tools

Zephyr Supported Hardware Architectures



Native execution on a POSIX-compliant OS

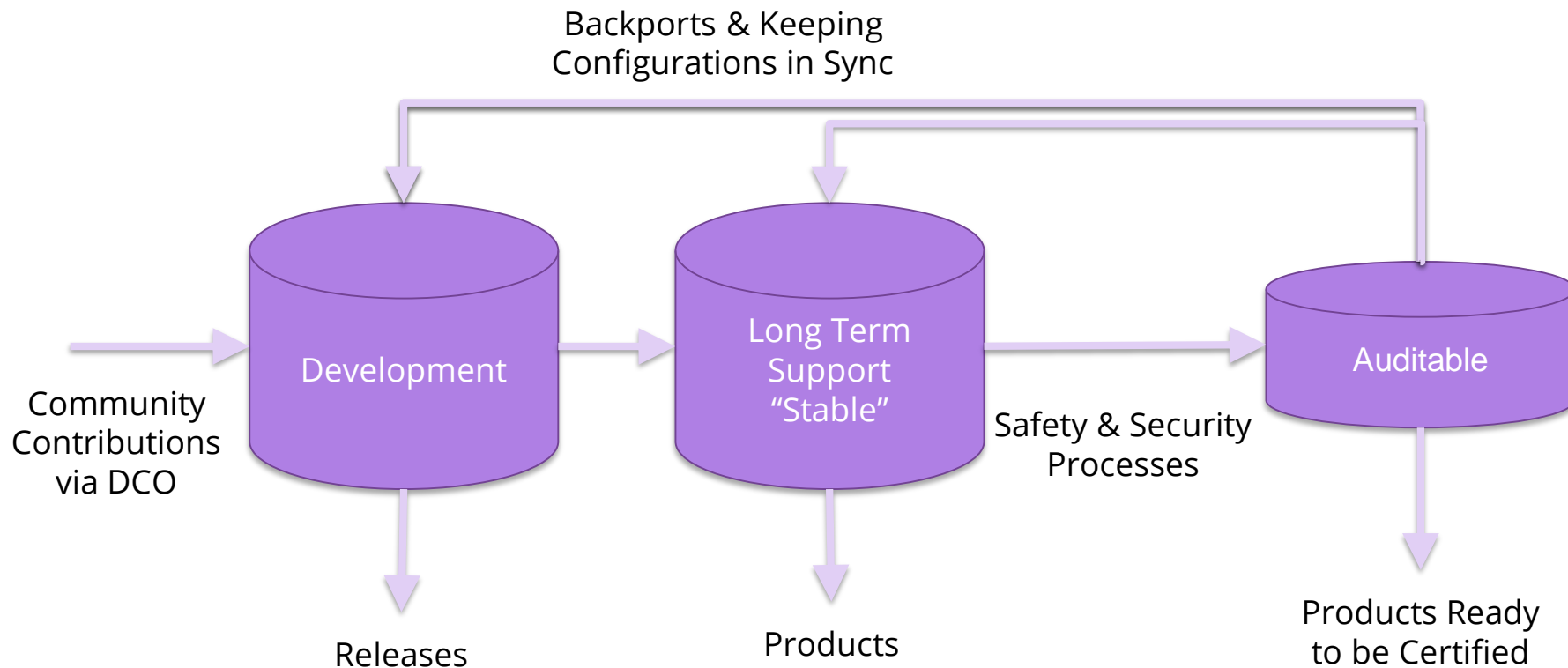
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What is next for Zephyr?

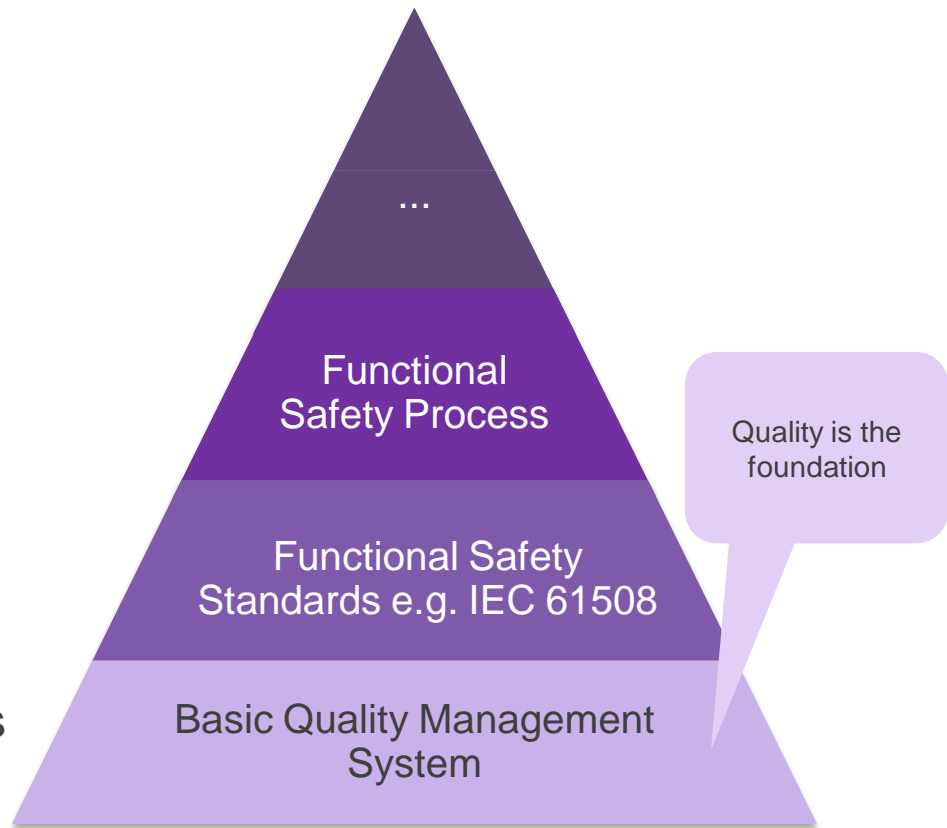
Security & Safety Certifications!

Code Repositories



Zephyr OS: Development

- Quality is a **mandatory expectation** for software across the industry.
- Assumptions:
 - Software Quality is enforced across Zephyr project members
 - Compliance to internal quality processes is expected.
- Software Quality is not an additional requirement caused by functional safety standards.
- Functional safety considers Quality as an existing pre-condition.



Zephyr OS: Long Term Support (LTS - 1.14)

It is:

- **Product Focused**
- **Current with latest Security Updates**
- **Compatible with New Hardware:** We will make point releases throughout the development cycle to provide functional support for new hardware.
- **More Tested:** Shorten the development window and extend the Beta cycle to allow for more testing and bug fixing

It is not:

- **A Feature-Based Release:** focus on hardening functionality of existing features, versus introducing new ones.
- **Cutting Edge**

Building in Security for LTS & Auditable

- Established **Security Committee**, meets bi-weekly.
- Secure Coding Practices have been [documented](#) for project.
- Zephyr Project [registered as a CVE Numbering Authority](#) with MITRE.
- Security Working Group has vulnerability response criteria publicly documented
 - addressed weaknesses and vulnerabilities already
- Passing Best Practices for projects as defined by CII
 - <https://bestpractices.coreinfrastructure.org/projects/74>
- Leveraging Automation to prevent regressions:
 - Weekly Coverity Scans to detect bad practices in imported code
 - MISRA scans being incorporated, to evolve to conformance and address issues.

Zephyr OS: Auditable Considered Standards

Coding for Safety, Security, Portability and Reliability in Embedded Systems:

- [MISRA C:2012](#), with [Amendment 1](#), following [MISRA C Compliance:2016](#) guidance

Safety:

- [IEC 61508: 2010](#) (SIL 3 initially, eventually though like to get to SIL 4)
 - broadest for robotics and autonomous vehicle engineering companies. Reference for other standards in Robotics domain.
 - [Sampled Certifications derived from IEC 61508](#): Medical: IEC 62304; Auto: ISO 26262; Railway: EN 50128

Security:

- PSA (Level 1+), [Common Criteria](#) (EAL4+), FIPS(140-2)

Others:

- Medical: FDA 510(K), ISO 14971, IEC 60601; Industrial: UL 1998, ??

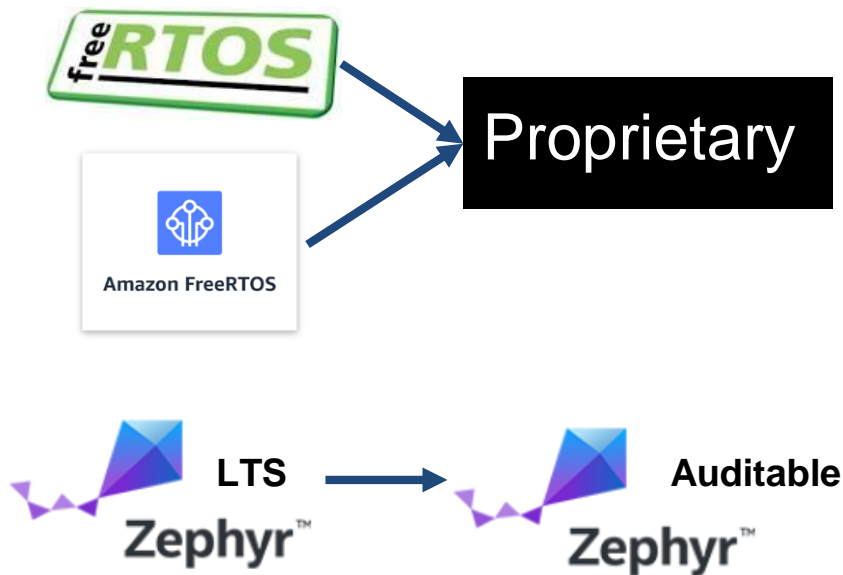
Zephyr OS: Auditable

- Initial target was decided by Governing Board to be **61508** (it is a common basis for others standards that the members care about)
- An auditable code base will be established from a subset of the **Zephyr OS LTS**.
 - Code bases will be kept in sync.
 - More rigorous processes (necessary for certification) will be applied to the auditable code base.

Processes to achieve selected certification to be determined by **Safety** Committee and **Security** Committee and coordinated with **Technical Steering** Committee.

Options for Safety Certification?

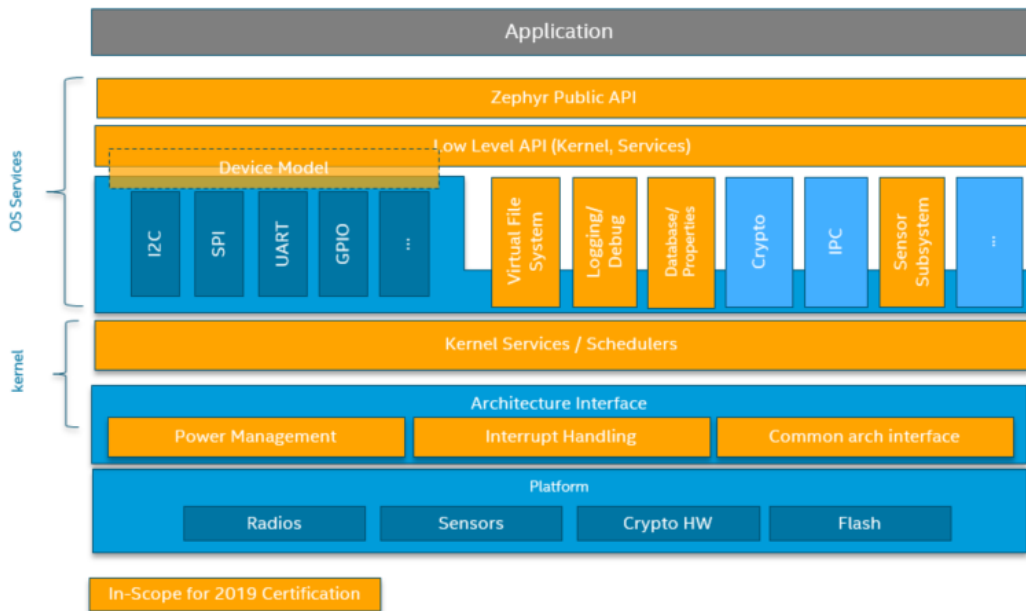
Explicit Path



2019 Auditable Scope (in orange)

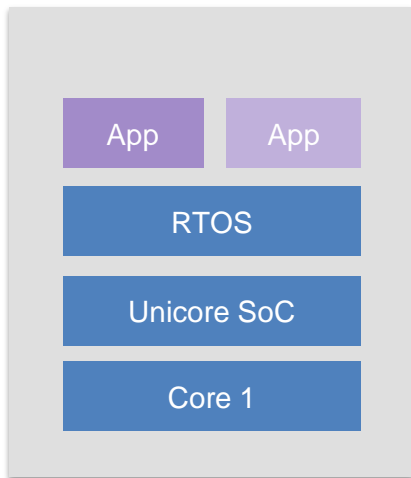
Not in scope:

- Platform drivers or BSPs
- No platform specific power management implementation, only device and kernel part of power-management
- No filesystem or sensor driver implementation, only interface and infrastructure to support those on top of existing APIs

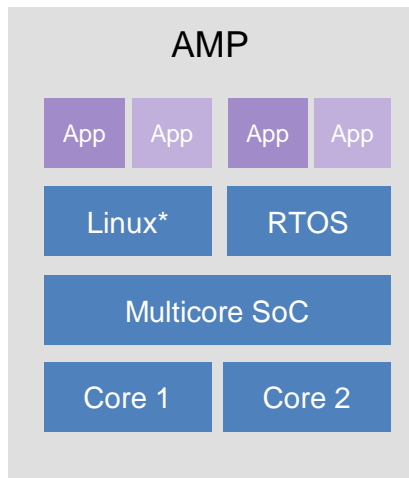


See: <https://www.zephyrproject.org/zephyr-project-rtos-first-functional-safety-certification-submission-for-an-open-source-real-time-operating-system/> for more details

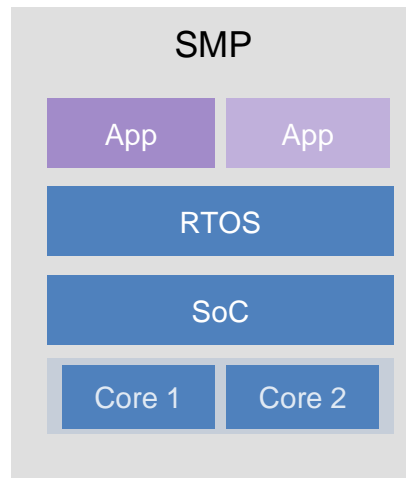
Zephyr Use Cases



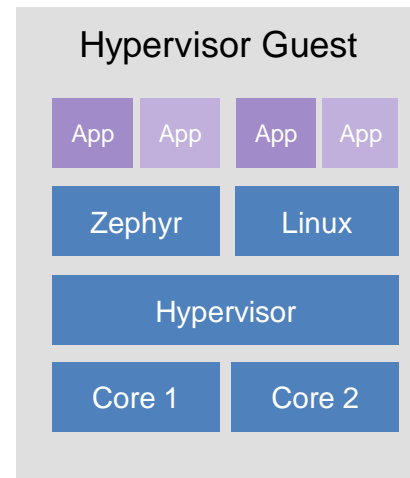
Single Core
MCU



Supported
with OpenAMP



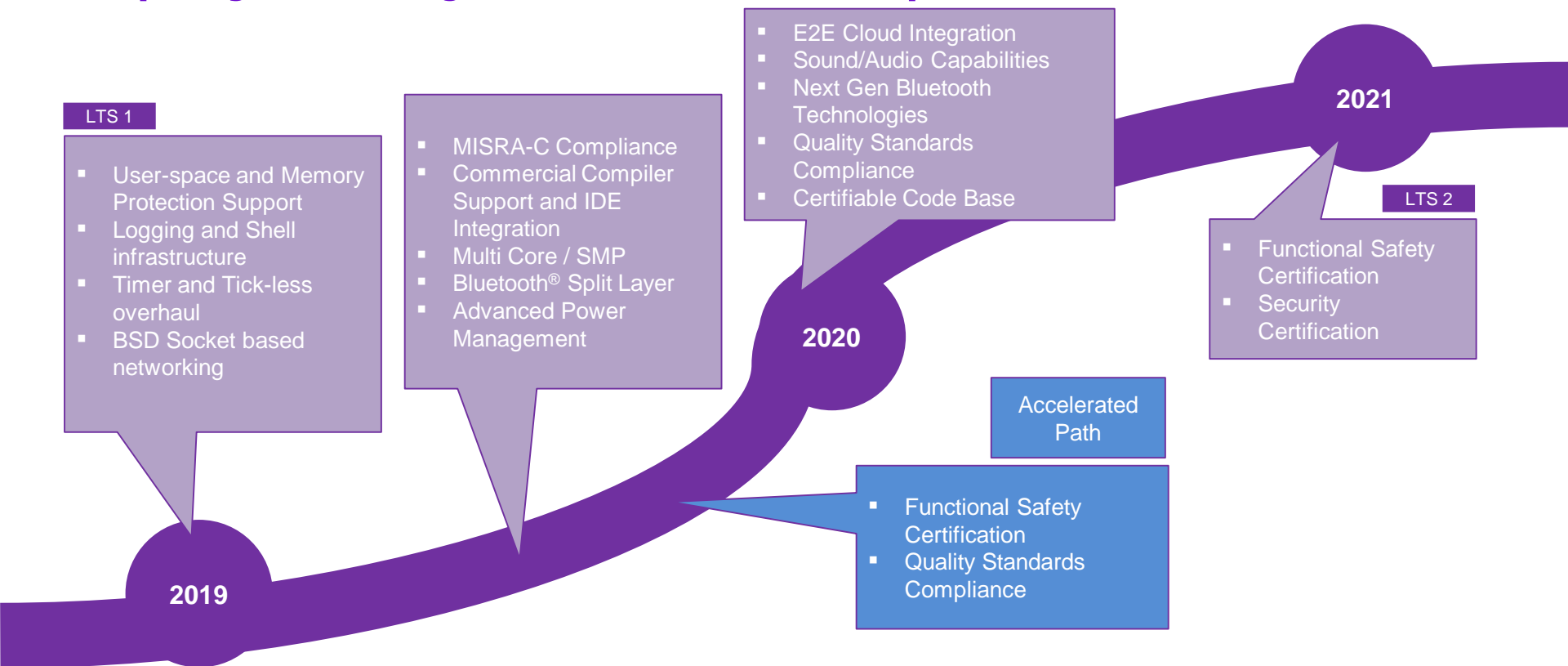
Supported
on Xtensa* and x86_64



Supported
with OpenAMP

Safety and security requirements grow with complexity of use cases

Zephyr Project Roadmap



Zephyr Participation Information

Orientation:

- <https://www.zephyrproject.org/community/how-to-contribute>
- <https://www.zephyrproject.org/doc/contribute/index.html>

Github:

- <https://github.com/zephyrproject-rtos/zephyr>

Mail Lists:

- <https://lists.zephyrproject.org/g/main>

Slack:

- <https://zephyrproject.slack.com> (get invite from github page)



www.zephyrproject.org